1 Basic mathematical concepts and rigorous proofs

References: [2, 4, 10]

- 1. Prove that, for all integers $n \ge 1$, the term $n^3 n$ is divisible by 3.
- 2. Let L_n be defined by $L_1 = 1$, $L_2 = 3$ and

$$L_n = L_{n-1} + L_{n-2}, \quad \text{for} \quad n \ge 3.$$

Use induction to show that

$$L_n \ge \frac{1}{2} \left(\frac{3}{2}\right)^n$$
, for all $n \ge 1$.

- 3. Prove that the set of prime numbers is not a finite set.
- 4. Prove that the set of rational numbers \mathbb{Q} is countably infinite. Then prove that the set \mathbb{Q}^d of *d*-tuples of rationals is countably infinite, for any $d \in \mathbb{N}$.

2 Analysis

References: [8, 11, 13, 14, 15]

- 1. Given a sequence $(a_n)_{n \in \mathbb{N}}$ of real numbers, give the definition of its infimum, supremum, limit inferior, limit superior, and limit. Give an example of a sequence that has no limit.
- 2. Given a sequence $(a_n)_{n \in \mathbb{N}}$ of real numbers, give the definition of the quantity $\sum_{i \in \mathbb{N}} a_i$. Describe sufficient conditions on the sequence such that the quantity $\sum_{i \in \mathbb{N}} a_i$ exists and is finite.
- 3. Give the definition for a function $f : \mathbb{R} \to \mathbb{R}$ to have the following properties at a point $x \in \mathbb{R}$: (i) left-continuity; (ii) right-continuity; (iii) continuity. Give the definition of a uniformly continuous function.
- 4. Give the definition of the derivative of a function $f : \mathbb{R} \to \mathbb{R}$ at a point $x \in \mathbb{R}$ and give the geometric interpretation of the derivative. Generalise this to the case where $f : \mathbb{R}^d \to \mathbb{R}$ for $d \in \mathbb{N}, d \geq 2$.

- 5. Define the Riemann integral of a function $f : \mathbb{R} \to \mathbb{R}$ in terms of a limit.
- 6. State the following theorems (including their hypotheses): (i) the intermediate value theorem; (ii) the mean value theorem; (iii) the fundamental theorem of calculus.
- 7. Let $d \in \mathbb{N}$, d > 1, and $f : \mathbb{R}^d \to \mathbb{R}$. Let $k \in \{1, \ldots, d\}$ and define the k-th partial derivative $D_k f$ of f. Define the gradient of a scalar-valued, continuously differentiable function on \mathbb{R}^d , and the divergence of a continuously differentiable function $f : \mathbb{R}^d \to \mathbb{R}^d$.
- 8. State a theorem about the existence and uniqueness of solutions to ordinary differential equations. Describe the main points of the proof of this theorem.
- 9. Consider the following differential equation in \mathbb{R}^2 :

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix}' = \begin{pmatrix} 2 & -8 \\ -8 & -17 \end{pmatrix} \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}.$$

- State whether there exists a solution to the differential equation, and whether this solution is unique.
- Describe the long-time behaviour of solutions and their dependence on the initial condition $(x(0), y(0))^{\top} \in \mathbb{R}^2$. Justify your answers.
- Draw the phase portrait of the differential equation.
- 10. Consider the flow associated to the following vector field on \mathbb{R}^2 :

$$F(x,y) = \begin{pmatrix} x(y-1) \\ -y^2 \end{pmatrix}.$$

Determine whether the flow has any critical points. If there are critical points, identify all of them.

- 11. State the Cauchy integral formula for holomorphic functions. Under what assumptions is this formula valid?
- 12. Use one or more theorems to justify why holomorphic functions are infinitely differentiable.

3 Linear Algebra

References: [5, 6, 12]

- 1. Let V, W be vector spaces and $\Phi: V \to W$ a linear map.
 - (a) What does it mean to say that a subset $U \subseteq V$ is a subspace?
 - (b) Define the kernel $\text{Ker}(\Phi)$ and show that it is a subspace of V.
 - (c) Prove that $\Phi: V \to W$ is injective if and only if $\text{Ker}(\Phi) = \{0\}$
- 2. Let $\Phi: V \to W$ be a linear map between finite dimensional vector spaces.

- (a) Define the rank of Φ and the nullity Φ .
- (b) Find the rank of Φ_A for the linear map $\Phi_A : \mathbb{R}^4 \to \mathbb{R}^3 : x \to Ax$ given by the matrix

$$A = \begin{bmatrix} 1 & 1 & 2 & 3 \\ 1 & 0 & 2 & 2 \\ 3 & 2 & 6 & 8 \end{bmatrix}.$$

- (c) How many vectors must there be in a basis for the null space of A? Briefly justify your answer.
- 3. Let V be a finite dimensional vector space over a field \mathbb{F} .
 - (a) Define the span $\{v_1, \ldots, v_n\}$ of a list of vectors $v_i \in V$.
 - (b) What does it mean to say that the list v_1, \ldots, v_n is (i) linearly independent (ii) a basis of V.
- 4. Let Φ be a linear operator on a finite-dimensional complex inner product space V with adjoint Φ^* , and let U be a subspace of V.
 - (a) Define what it means to say that U is a Φ -invariant subspace, and define the orthogonal space U^{\perp} .
 - (b) Show that if U is Φ -invariant, then U^{\perp} is Φ^* -invariant.
 - (c) State the Spectral Theorem for normal operators, using orthogonal projections.
- 5. In this question A, B and C are sets, $f : A \to B$ and $g : B \to C$ are maps and $h = g \circ f$ is the composed map so $h : A \to C$
 - (a) Suppose that h is surjective. Does it follow that f is surjective? Justify your answer.
 - (b) Suppose that h is injective. Does it follow that f is surjective? Justify your answer.

4 Measure theory

References: [7]

- 1. Define a sigma-algebra \mathcal{F} on a nonempty set Ω . What does it mean for a sigma-algebra to be countably generated? What does it mean for \mathcal{G} to be a sub-sigma algebra of \mathcal{F} ?
- 2. Let $d \in \mathbb{N}$ be arbitrary. Define the Borel sigma-algebra on \mathbb{R}^d .
- 3. Define what a measurable space is and what a measure on a measurable space is.
- 4. Let (S_1, \mathcal{S}_1) and (S_2, \mathcal{S}_2) be two measurable spaces. What does it mean for a function $f: S_1 \to S_2$ to be $(\mathcal{S}_1, \mathcal{S}_2)$ -measurable?
- 5. State the invariance properties of d-dimensional Lebesgue measure on \mathbb{R}^d .

- 6. Define the Lebesgue integral on \mathbb{R} . For a subset S of \mathbb{R} , let \mathbb{I}_S denote the indicator function of S, and let \mathbb{Q} denote the set of rational numbers. Calculate the value of the Lebesgue integral $\int_{\mathbb{R}} \mathbb{I}_{\mathbb{Q}}(x)$ Leb(dx), where 'Leb' denotes Lebesgue measure.
- 7. State the monotone convergence theorem, the dominated convergence theorem, and Fatou's lemma.
- 8. Let μ, ν be two measures on a measurable space (S, S). Define what it means for μ to be absolutely continuous with respect to ν and what it means for μ and ν to be mutually equivalent. Give an example of two measures μ and ν such that μ is absolutely continuous with respect to ν but not mutually equivalent to ν .

5 Geometry / topology

References: [9]

- 1. Give the definition of a topology on a nonempty set and define all the terms that you use in the definition.
- 2. What does it mean for a topology to be Hausdorff?
- 3. Define what is a homeomorphism of topological spaces.
- 4. Give the definition of a connected set, a path connected set, and a simply connected set. Give an example of a set that is connected but not path connected.
- 5. Give the definition of a d-dimensional real manifold. Give an example of a 2-dimensional real manifold.
- 6. What is the tangent space to a manifold M at a point $p \in M$? What is the tangent space to the example of the 2-manifold you gave for the previous question?
- 7. A non-empty intersection of two planes in \mathbb{R}^3 is a line. Prove that a non-empty inter-section of two spheres in \mathbb{R}^3 is a circle (considering a point as a circle of radius 0).
- 8. Let $\gamma : \mathbb{R} \to \mathbb{R}^2$ be a regular unit-speed smooth curve such that all tangent lines to γ intersect in a point. Show that γ is a straight line.
- 9. Let S be a compact connected surface which is not homeomorphic to a sphere. Show that there are points on S where the Gaussian curvature is positive, negative and zero.
- 10. Let α be a space curve with an arbitrary regular parametrization. Show that its curvature is given by

$$\kappa(t) = \frac{||\dot{\alpha} \times \ddot{\alpha}||}{||\dot{\alpha}||^3}.$$

11. Define the *catenoid* as the surface S_f parametrized by

$$f(u, v) = (\cosh u \cos v, \cosh u \sin v, u)$$

and the *helicoid* as the surface S_q parametrized by

 $g(u, v) = (\sinh u \cos v, \sinh u \sin v, v).$

- (a) Show that, for any point $(u, v) \in \mathbb{R}^2$, the Gaussian curvature of S_f at f(u, v) coincides with the Gaussian curvature of S_g at g(u, v).
- (b) Show that the mean curvature of both S_f and S_g is identically zero.

6 Probability theory

References: [1, 3]

- 1. Define a probability space and define every object involved in the definition.
- 2. State what sigma-additivity or countable additivity of a probability measure means.
- 3. Let E be a nonempty set. Give the definition of an E-valued random variable X on a probability space $(\Omega, \mathcal{F}, \mathbb{P})$. Then, define the cumulative distribution function (c.d.f.) of X and state all the properties that imply a function $F : \mathbb{R} \to \mathbb{R}$ is the cumulative distribution function of a \mathbb{R} -valued random variable.
- 4. Give the definition of mutual independence of a collection of measurable events, and of a collection of random variables. Let X and Y be two \mathbb{R} -valued random variables on a probability space. Define such that the covariance of X and Y is zero. Does this imply that X and Y are independent? If yes, then give a proof. If not, then give a counterexample.
- 5. If two random variables are equal in distribution, does this imply they are equal almost surely? If yes, then give a proof. If not, then give a counterexample.
- 6. Let (X, Y) be a \mathbb{R}^2 -valued random variable with joint p.d.f. $f_{X,Y}$. Define the marginal p.d.f. f_X and the conditional p.d.f. $f_{X|Y}$.
- 7. Let X be a \mathbb{R}^d -valued random variable on a probability space $(\Omega, \mathcal{F}, \mathbb{P})$ and let $p \geq 1$. Define what it means for X to belong to $L^p(\mathbb{P})$.
- 8. Give the definition of a probability density function (p.d.f.) of a \mathbb{R}^d -valued random variable. Write down the formula for the p.d.f. of a \mathbb{R}^d -valued normal random variable with mean $m \in \mathbb{R}^d$ and strictly positive definite covariance matrix $C \in \mathbb{R}^{d \times d}$. Make sure to specify all the necessary assumptions on m and C for the equation to be valid.

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